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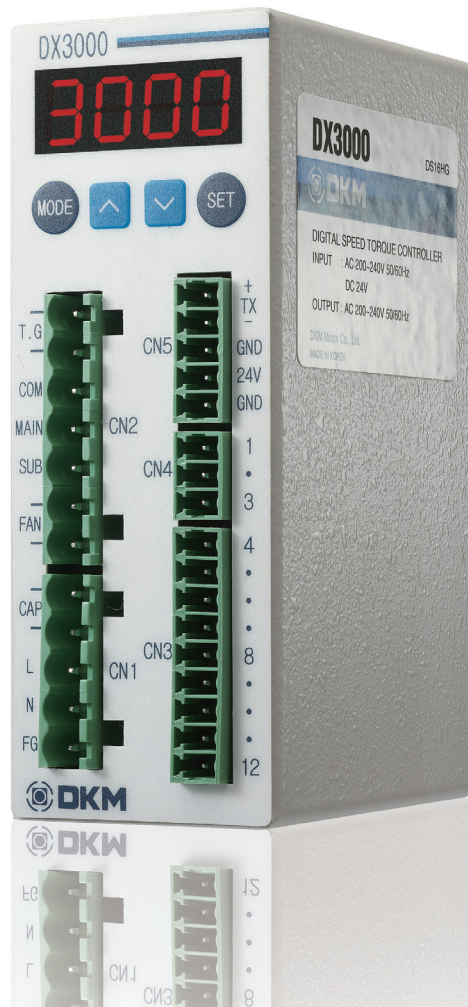
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DKM Speed Controller

DKM Speed Controller



DKM Controller

Line-Up

Unit Type



FX3000

- Digital Speed Display
- Speed, Torque Control
- Simple Dial
- Gear Ratio Setting
- Acceleration Time Setting



DSA

- Analog Type
- Speed Control

※ Unit type controller, FX3000 and DSA have built-in capacitor, so there is no need to connect a separate capacitor.

Din-Rail Type



DX3000

- RS485 Communication Control
- PLC I/O Control
- Speed, Torque Control
- Four Stage Speed(Torque) Setting
- Gear Ratio Setting
- Acceleration Time Setting



DSKM

- Socket Type Controller
- Multi-Stage Speed Setting (Install external volume separately)
- Electric Brake Function (Install resistance coil separately)

※ DIN-Rail type controller, DX3000 and DSKM should install capacitor same as the motor rated output.

General Specifications

Title	AC Speed Controller				
	DSA	DSKM	FX1000 (Will be discontinued)	FX3000	DX3000
Input Power	1Ø220~240V 50/60Hz	1Ø220~240V 50/60Hz 1Ø100~120V 50/60Hz	1Ø220~240V 50/60Hz	1Ø220~240V 50/60Hz	1Ø220~240V 50/60Hz
Output(W)	6W~180W	6W~180W	6W~180W	3W~180W	3W~180W
Display	-	-	4 DIGIT DISPLAY	4 DIGIT DISPLAY	4 DIGIT DISPLAY
Speed Control Range	50Hz : 90~1400r/min 60Hz : 90~1700r/min	50Hz : 90~1400r/min 60Hz : 90~1700r/min	50Hz : 90~1400r/min 60Hz : 90~1700r/min	50Hz : 90~1400r/min 60Hz : 90~1700r/min	50Hz : 90~1400r/min 60Hz : 90~1700r/min
Torque Control Range	-	-	-	0~100%	0~100%
Speed Setting	Internal Volume	Internal Volume, External Volume	Internal Volume	Internal Volume	DIGITAL, External Volume, DC Voltage, RS485 Communication
Multi-stage Speed Setting	-	External Volume	-	-	External Volume Internal Setting RS485 Communication
Operation Command	Power On/Off	Power On/Off	Power On/Off	Power On/Off I/O Command	I/O Command RS-485 Communication
Acceleration Time Setting	-	-	-	0.1~15sec	0.1~15sec
Gear Ratio Setting	-	-	-	0	0
Gain Setting(P, I)	-	-	-	0	0
Zero Clamp	-	-	-	-	0
Speed Command Offset	-	-	-	-	0
Communication	-	-	-	-	Serial Communication(RS485)

Combination Table

Model	W	Motor Model	Controller			
			FX3000	DX3000	DSA	DSKM
SPEED MOTOR	6W	6SD□□-6□	FX3000-006 S	DX3000	DSA-006	DSKM
		7SD□□-6□				
	10W	7SD□□-10□	FX3000-010 S		DSA-010	
	15W	7SD□□-15□	FX3000-015 S		DSA-015	
		8SD□□-15□				
	25W	8SD□□-25□	FX3000-025 S		DSA-025	
	40W	9SD□□-40□	FX3000-040 S		DSA-040	
	60W	9SD□□-60F2□	FX3000-060 S		DSA-060	
	90W	9SD□□-90F2□	FX3000-090 S		DSA-090	
	120W	9SD□□-120F2□	FX3000-120 S		DSA-120	
180W	9SD□□-180F2□	FX3000-180 S	DSA-180			
TORQUE MOTOR	3W	6TD□□-3□	FX3000-003 T	DX3000	-	-
	6W	7TD□□-6□	FX3000-006 T			
	10W	8TD□□-10□	FX3000-010 T			
	20W	9TD□□-20F2□	FX3000-020 T			
	30W	9TD□□-30F2□	FX3000-030 T			
	40W	9TD□□-40F2□	FX3000-040 T			
	60W	9TD□□-60F2□	FX3000-060 T			

CAUTION

- About FX3000/ DSA controller, capacitor is built-in type and capacity is different according to the motor output. Please check the controller model name and motor output surely.
- About FX3000/ DX3000, initial control mode is speed control. Please change the parameter to torque control mode when using the controller with torque motor.

2018 DKM Controller

NEW 2018

 FX3000 Features and Advantages



Comfort, Convenient Dial
Dial Volume

Digital Speed Display
Digital Torque Display

Easy, Simple Wiring
Built-in Capacitor

Screwless
Connector

Gear Ratio Setting

Acceleration Time
Setting

Torque Control Function
Standard Speed Control

NEW 2018

DX3000 Features and Advantages

RS485 Communication
Standard Modbus

Digital Speed Display
Digital Torque Display

Space Saving
Unnecessary Relay

PLC I/O Control

Gear Ratio Setting

Acceleration Time
Setting

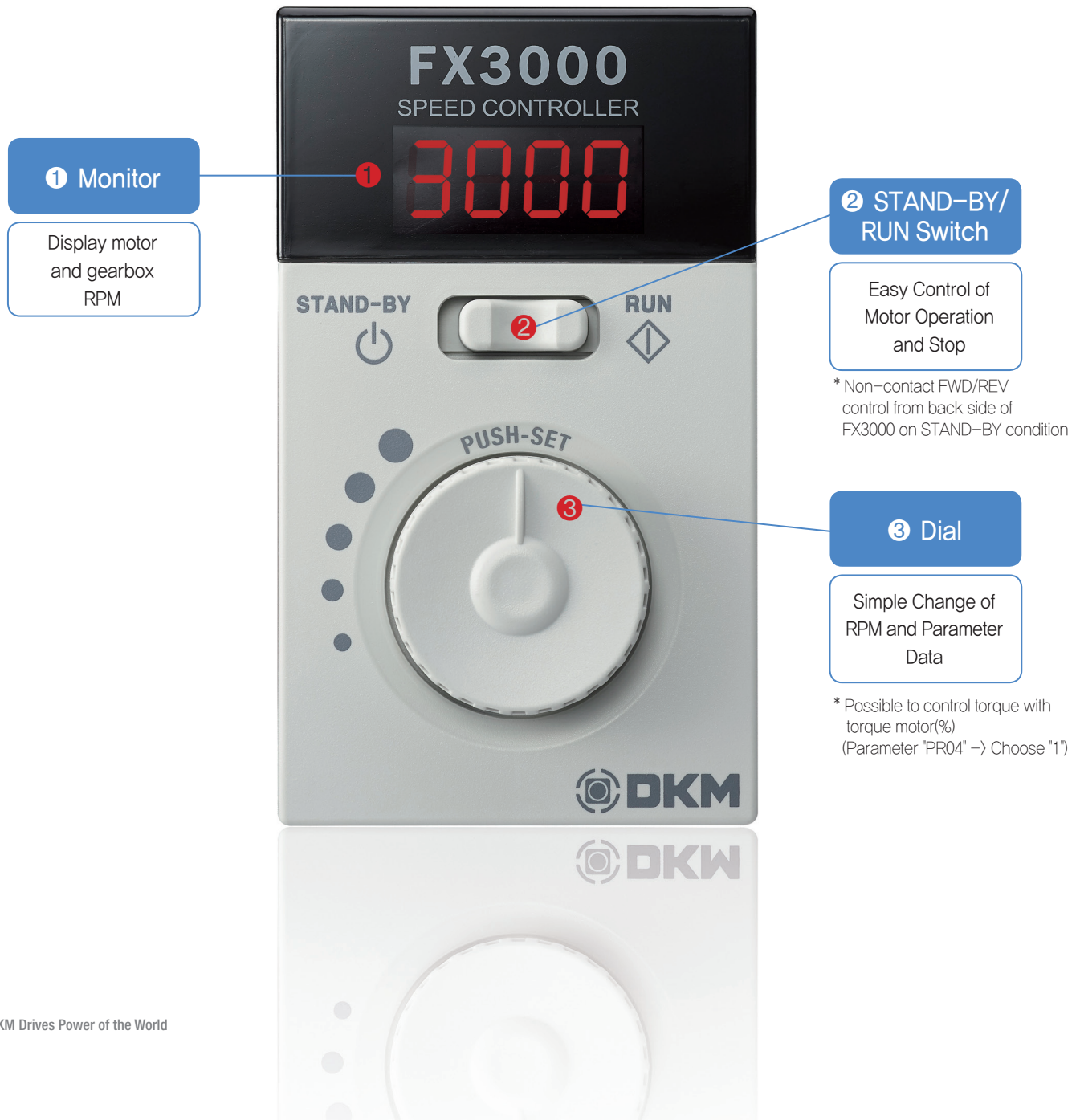
Torque Control Function
Standard Speed Control



FX3000

Product Formation (Front Side)

| Simple Control and Intuitive Design |



| Efficient and Convenient Operation |



FX3000

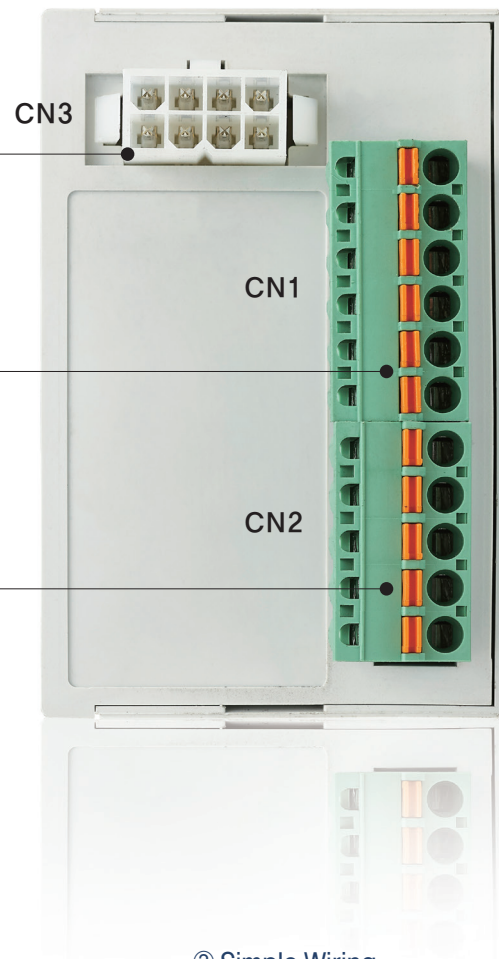
Product Formation (Back Side)

| Easy Wiring and Maintenance |

CN3 : Motor Connector Terminal
(Connect motor connector)

CN1 : Power Terminal(AC power)
FWD/REV Input Signal Terminal
(Connect if operating with external signal)

CN2 : Motor Terminal
(Connect lead wire type motor or
other brand motor)



① Built-in Capacitor



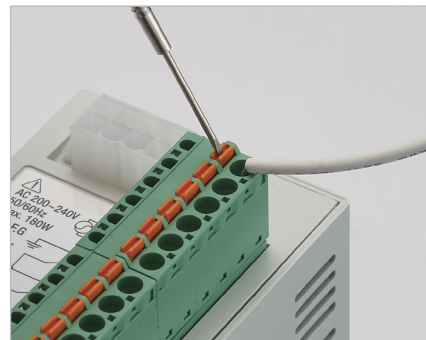
Unnecessary
Capacitor Wiring

② Simple Connection



One-touch Connection
of Motor and Controller

③ Simple Wiring



No Bolt, Screw Needed
Press orange button and insert lead wire

FX3000 Parameter

Various Parameter Function and Response to Customer Demand

Parameter Contents

Parameter		Function	Range	Standard Value	Remark
NO.	Display				
1	Pr01	Acceleration Time	0~15.0	0.1	Time(second) to reach the set speed
2	Pr02	Rotation Direction	0,1	0	0 : Clockwise 1 : Counterclockwise
3	Pr03	Gear Ratio	1~999	1.0	Input gear ratio
4	Pr04	Control Mode	0,1	0	0: Speed Control 1: Torque Control
5	Pr05	P Gain	0~255	100	
6	Pr06	I Gain	0~255	50	
7	Pr07	Parameter Reset	-	0	Reset when pressing and holding the SET button
SF	PrSF	Software Version	-	-	Display the software version



* Speed Control P, I gain

-Parameter which determines responsibility of speed control.

-Vibration and hunting may occur if the value is too great.

Parameter Setting Procedure



After wiring, set as follows.

① Input AC Power

Display lights up (Rotation speed)

② Select Parameter Mode

Enter into the parameter mode as pressing the MODE button while motor is stop condition. (STAND-BY)

"Pr01" appear at display (Parameter mode)

③ Parameter Data

Turn the dial and choose the parameter number which user wants to (Pr01~Pr07)

④ Change Parameter Data

Press the dial (SET button) to enter the parameter data.

CHANGE
PUSH Hold-2sec.
DATA flickers and switches to changeable status if pressing and holding the dial (SET button) during 2 sec.

CHANGE
CW/CCW Rotation
The data value is changed and the desired data value is set. When the dial is rotated by CW / CCW.

COMPLETE
PUSH Hold-2sec.
Data stop blinking and finish the setting when pressing and holding the dial (SET button) for 2 sec.

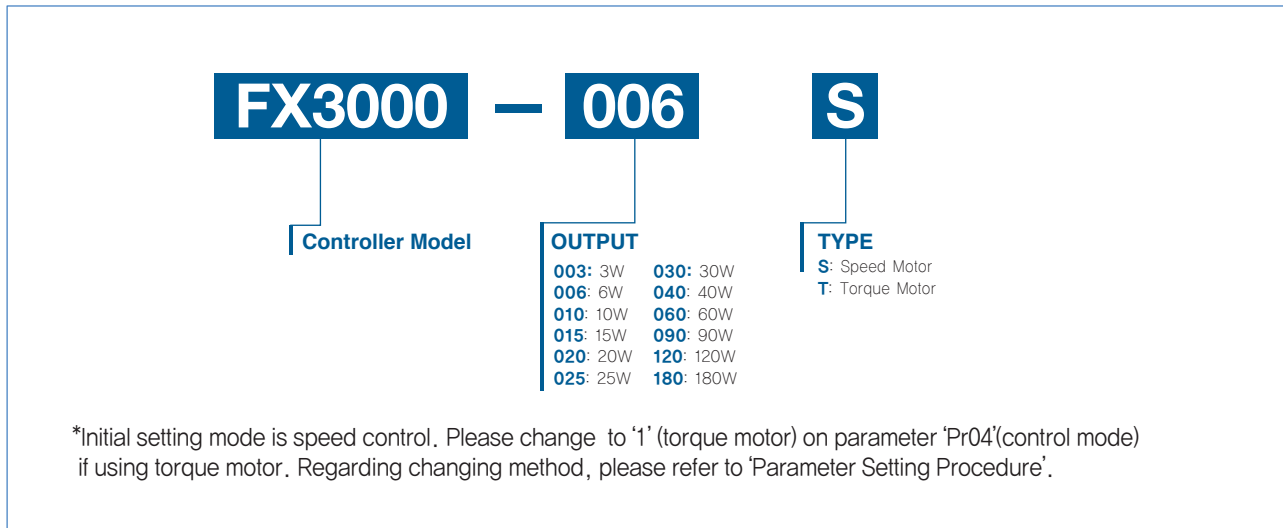
⑤ Operation Mode

Press the MODE button to enter the operation mode.

'0' on the display (Rotation speed) (operation mode)

FX3000

Controller Coding System



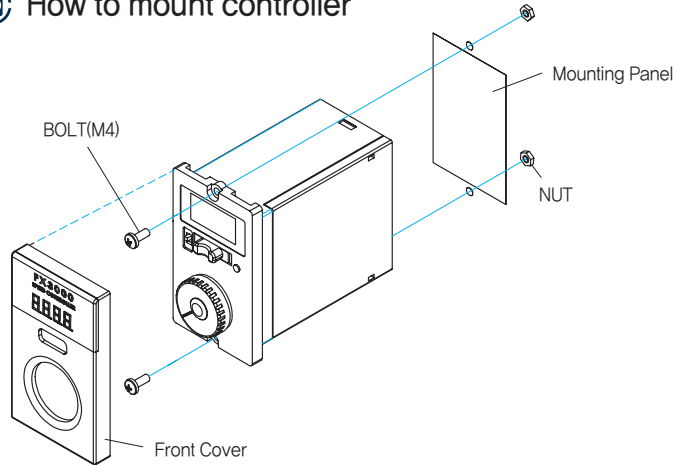
Special Features

- Possible to control speed and torque.
- Possible to control the speed and torque of the motor simply by connecting motor and control unit with connector and inputting the AC terminal to the power source.
- Display the current rotation speed(r/min) and torque(%).
- Possible to control speed and torque easily with the front panel dial.
- Possible to operate various functions by setting the parameter.

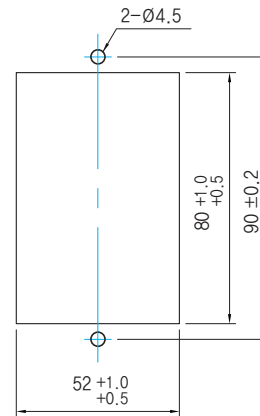
General Specifications

Model Name	FX3000-□□	
Rated Voltage	1∅ AC 220~240V 50/60Hz ±10 %	
Allowable Current	Below 6 A	
Control Function	Speed Control, Torque Control	
Control System	Phase Control	
Setting Range	Speed Control	50Hz : 90~1400r/min 60Hz : 90~1700r/min
	Torque Control	0 ~ 100 %
Speed Setting	Setting by Volume	
Speed Variation	±5%(Standard Value)	
Motor Output	3W~180W	
Ambient Temperature	-10C° ~ 55C°	
Ambient Humidity	35 ~ 85%RH (Without condensation)	
Insulation Resistance	Over DC 500V 100MΩ (between power supply and external terminal)	
Dielectric Strength	AC 1500V 1minute (between power supply and external terminal)	

How to mount controller



(Mounting Panel Dimension)

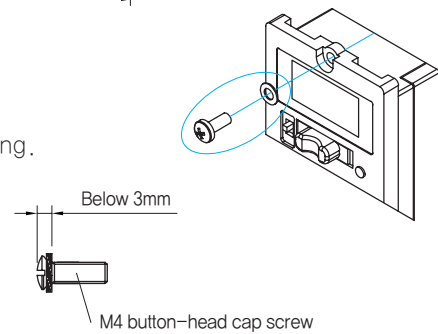


How to install

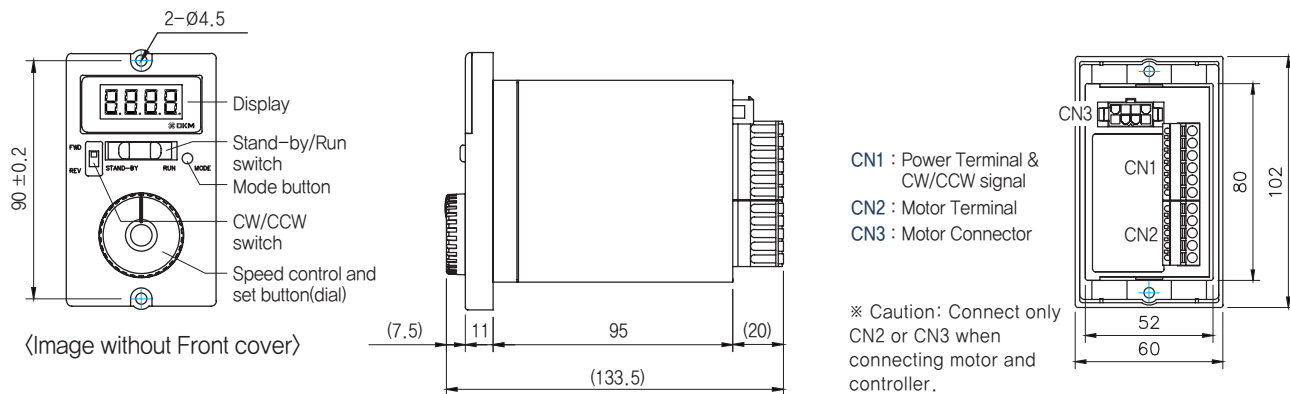
- Process the hole on the mounting panel to attach the controller.
- Fix the mounting panel and controller body with M4 bolt and nut.
- Cover the front cover after controller installation, operation and parameter setting.

Caution

- Install without gap between the controller and the mounting panel.
- The screw head fixed with controller should be below 3mm. If over 3mm, front cover can't be amounted.

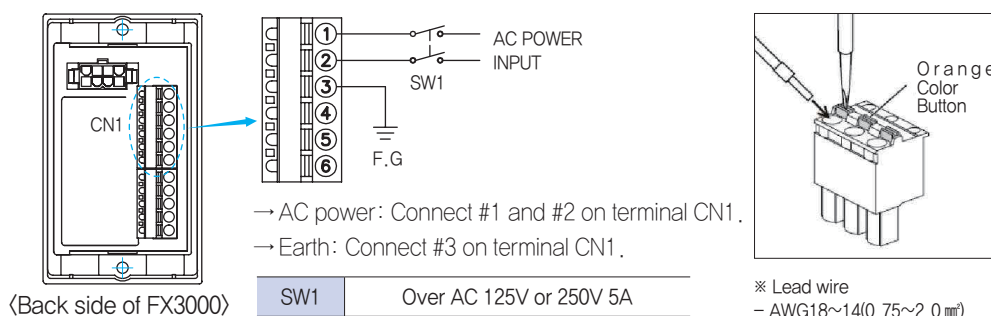


Each part name and Dimension



Connection

1. Controller Power Connection

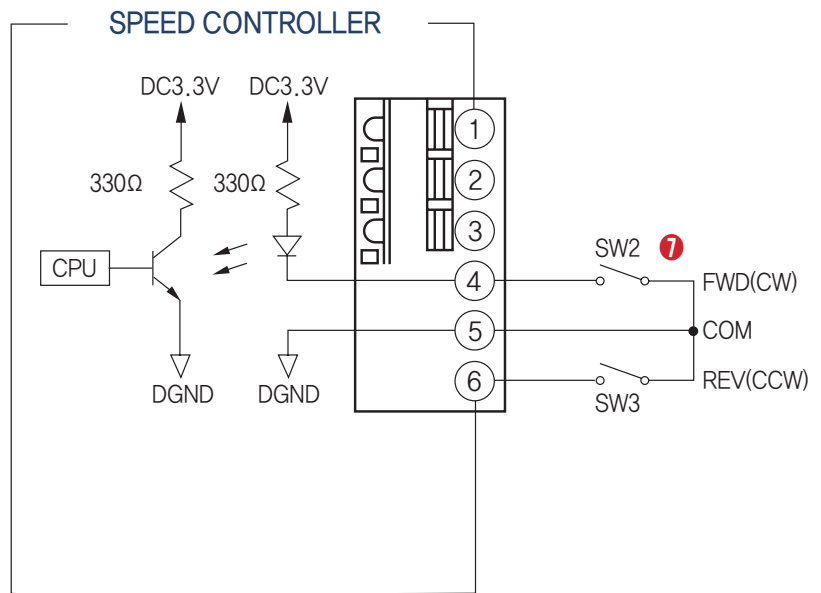
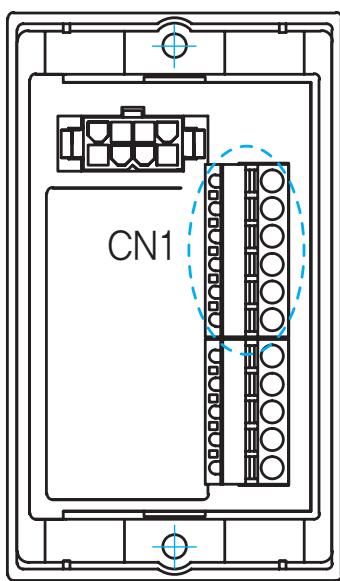


Lead wire connection

- Input the lead wire while pressing the orange color button with screw driver.

FX3000

| Non-contact control function for external control |



※ The above diagram shows the connection example when the motor is operated by relay or switch.

⑦ Non-contact FWD/REV control

Ⓢ Operation by External Signal

→ In case of RUN/ STOP operation externally, please make sure that switch position should be on STAND-BY and connect #4, #5, #6 on terminal CN1.

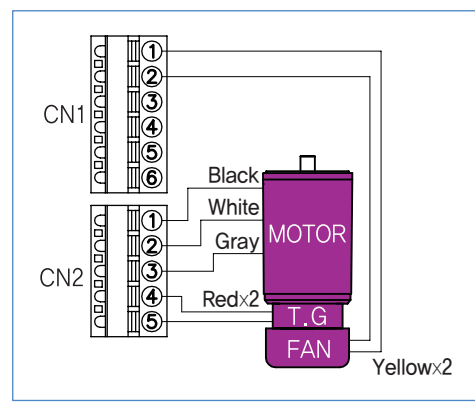
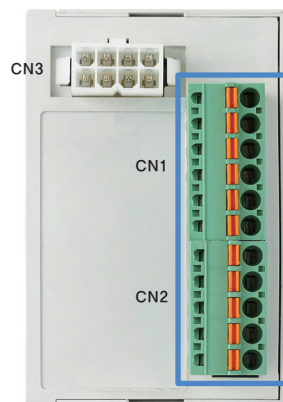
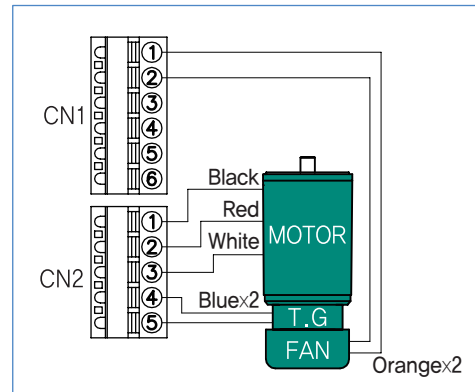
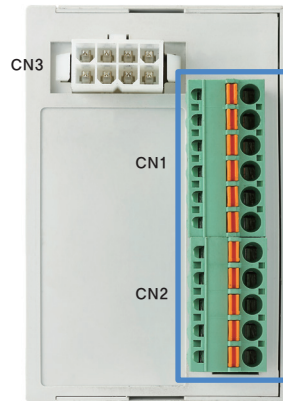
→ Input Signal Terminal(CN1)

SW2	SW3	Motor Shaft
ON	OFF	Rotate to FWD
OFF	ON	Rotate to REV
OFF	OFF	STOP

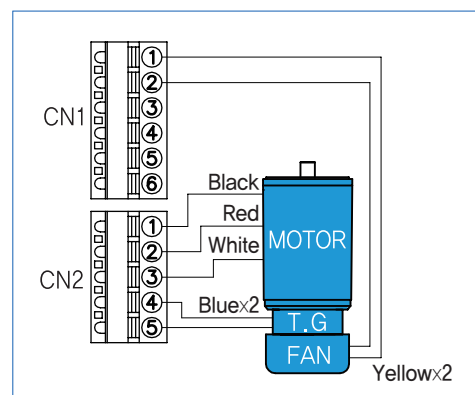
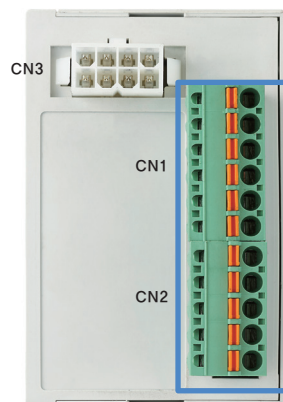
※ Connect only for external RUN/STOP.

※ Front switch should be at STAND-BY position when operating by external signal.

How To Connect Other Brand Motor

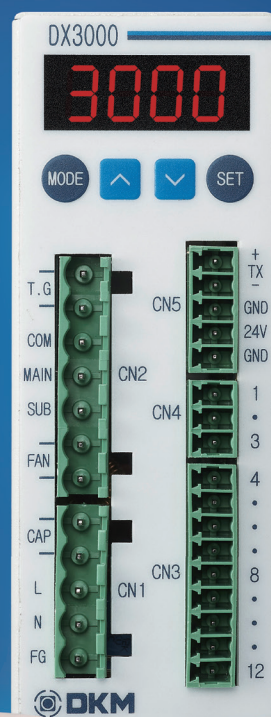


Red



- Do not connect to CN3 when connecting other brand motor.
- According to the motor type, TG wire(gray*2) and powerful fan wire(black*2) may not be in.
- Please contact us before using other brand motor.

New Digital Controller Launching!



NEW

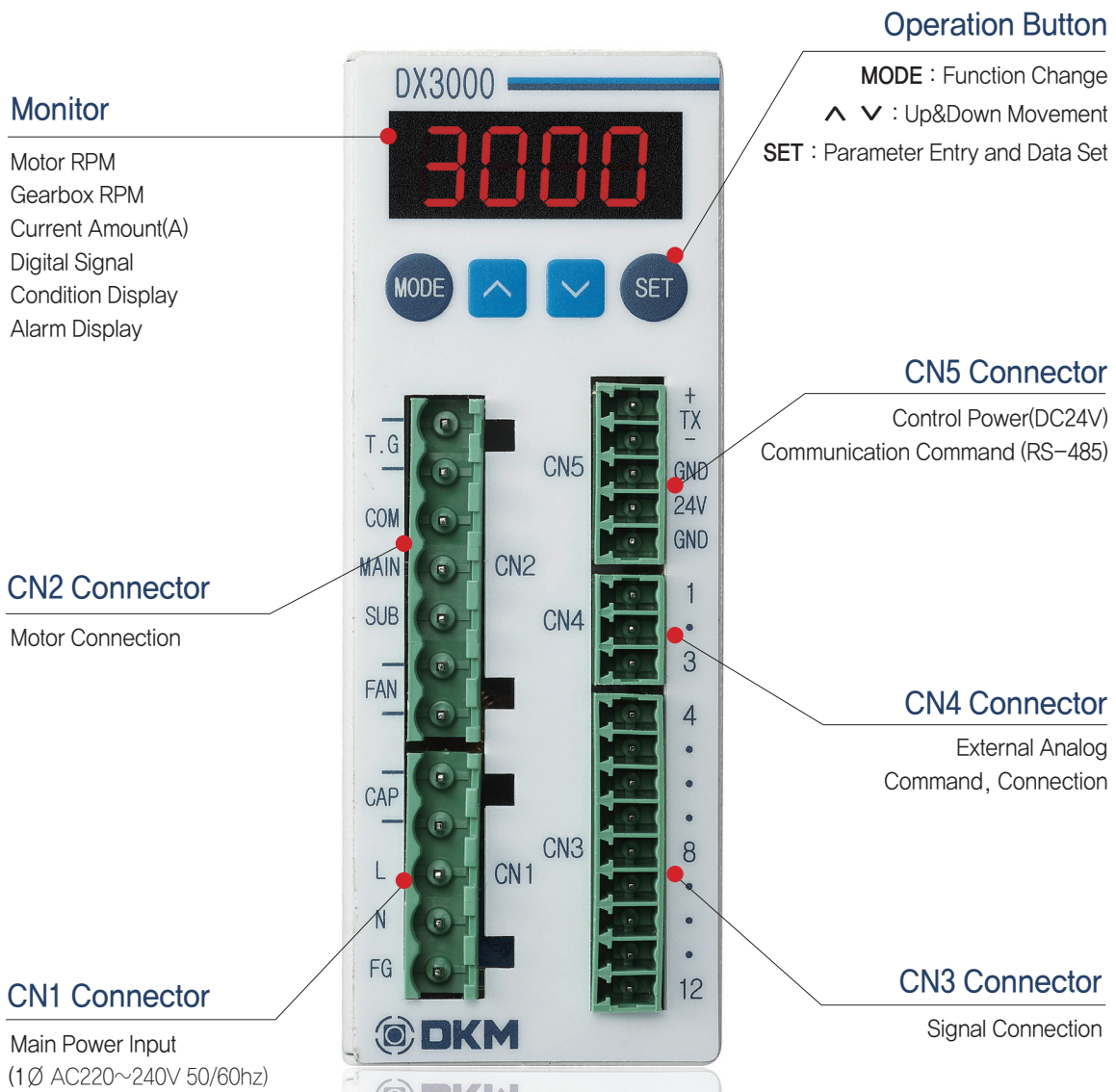
DX3000 Main Functions

- PLC I/O Command
- Easy Connection
- Four Stage Speed Setting
- RS485 Communication
- Unnecessary Relay
- Gear Ratio Setting
- Torque, Speed Motor Control

 **DKM** MOTOR SERIES
motor & gearbox



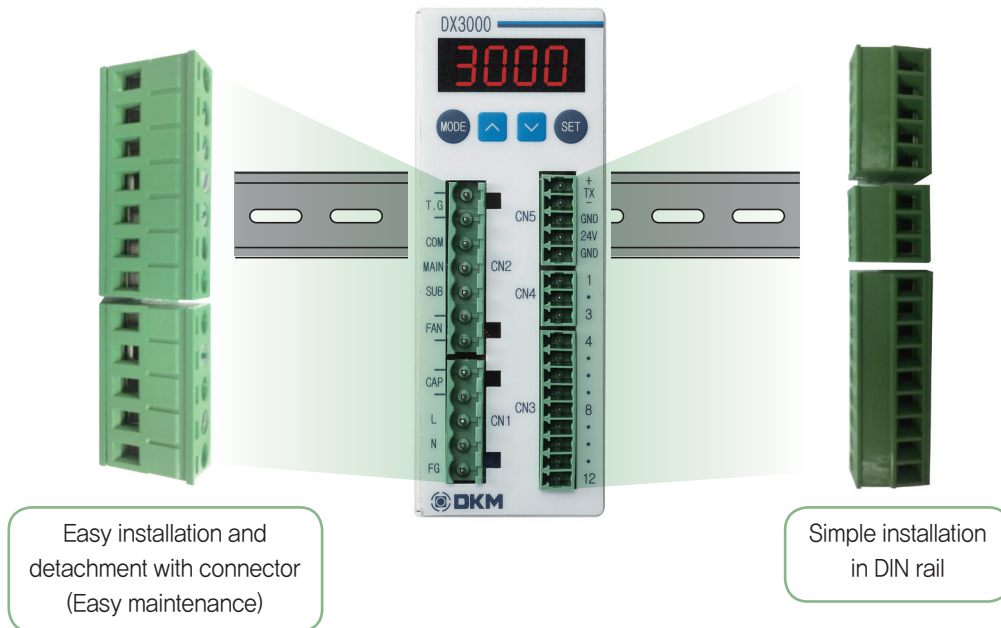
Product Formation (Front Side)



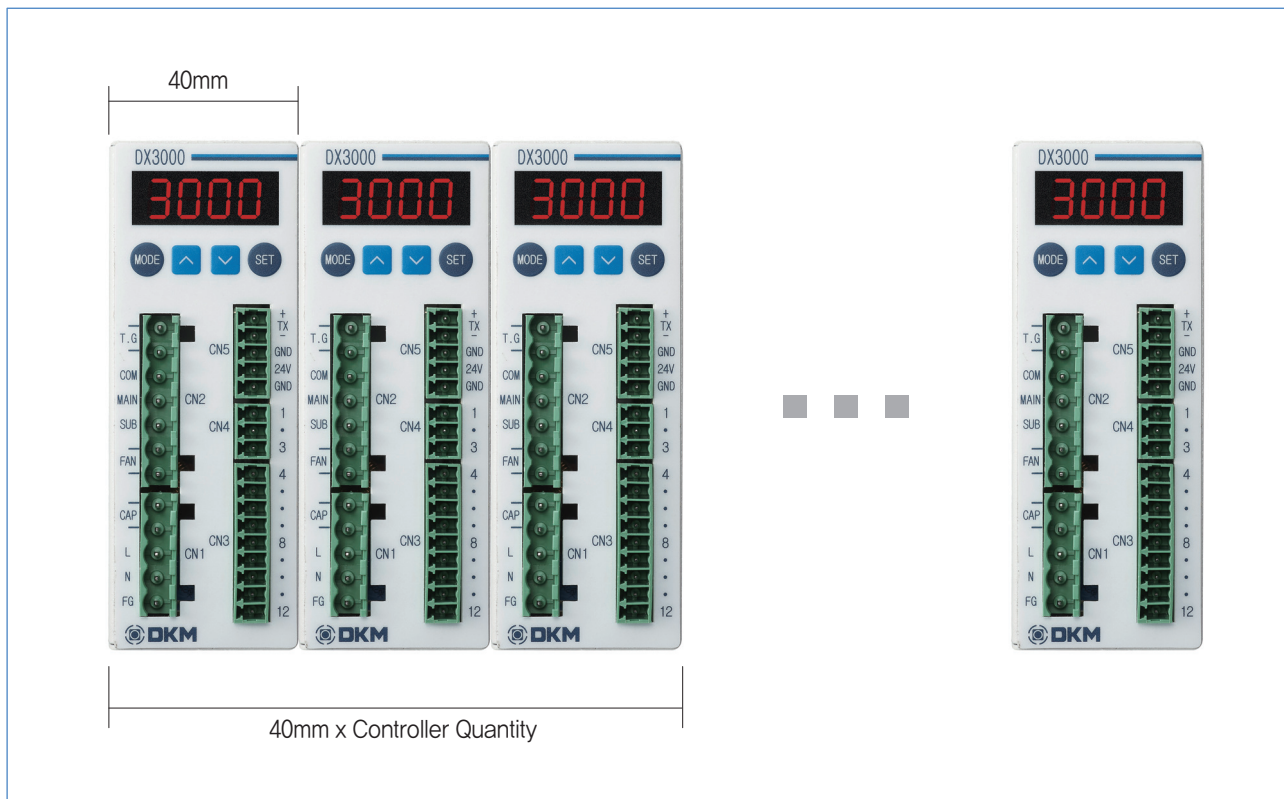
DX3000

DX3000 Features and Advantages

- Easy, Simple Wiring and Maintenance

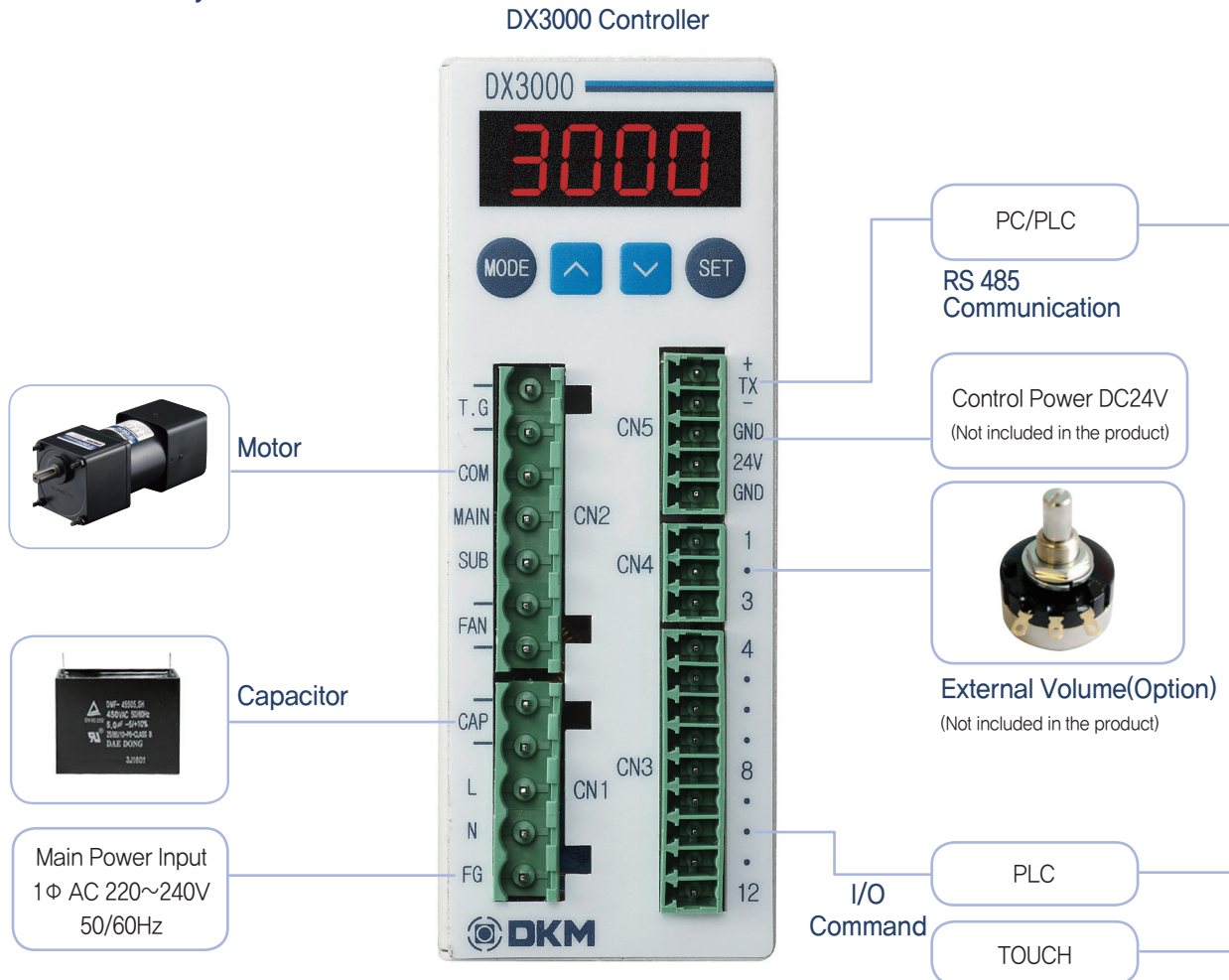


- Space Saving



**Possible to install closely in DIN rail (Controller Width 40mm)

■ Controller System



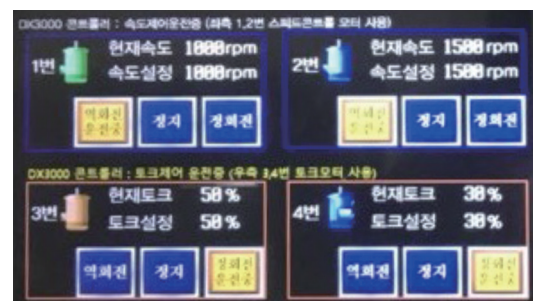
■ Simplification of peripheral devices

RS 485 Communication System



Unnecessary Relay

- Security of space inside of panel
- Simple wiring and reducing cost
- Reduction of labor force
- Easy maintenance



*RS485 communication control system with PLC and touch screen



Parameter Contents

NO.	Function	Range	Standard value	Note
1	Max. Speed	1460/1760	–	r/min
3	Speed Limit	50~1760	1760	r/min
4	Acceleration Time	0~15.0	0.1	Second (S)
5	Rotation Direction	0~1	0	
6	Gear Ratio	1~250	1	
7	Control Mode	0~1	0	0 : Speed Control 1 : Torque Control
8	Zero Clamp	0~5.0	0.0	Voltage (V)
9	Speed Command Offset	0~5.0	0	Voltage (V)
10	Abnormal Signal Output	0~1	0	
13	Speed Control P Gain	0~255	100	
14	Speed Control I Gain	0~255	50	
20	Communication ID Setting	1~254	1	
21	IO Input Setting	0~1	0	0 : CN3 IO Input 1 : RS485 Input
22	Speed Input Setting	0~1	0	0 : CN4 Potentiometer Input 1 : RS485 Speed Command input
30	Internal Speed Setting 1	0~Max. Speed	500	r/min
31	Internal Speed Setting 2	0~Max. Speed	1000	r/min
32	Internal Speed Setting 3	0~Max. Speed	1500	r/min
33	Internal Torque Setting 1	0 ~ 100	10	%
34	Internal Torque Setting 2	0 ~ 100	20	%
35	Internal Torque Setting 3	0 ~ 100	50	%

■ No.1 Max. Speed

- Function to check the max. speed – setting impossible
- Max. speed changes automatically according to input power's frequency(50/60Hz)
- 50Hz : 1460 r/min, 60Hz : 1760 r/min
- When inputting speed command voltage(VR), find maximum RPM operated at maximum input voltage (external: 5V, internal: 100)

■ No.3 Speed Limit

- Set when user wants to limit motor speed
- Set value is only applied when set value is lower than max. speed of motor
- The speed limit is same as max. speed if the speed limit is higher than max. speed
- Regarding torque motor, it's possible to attach T.G(Customized order)

■ No.4 Acceleration Time

- Set the time taken to reach the parameter No.1
- Accelerate at set time if controller acceleration VR is 100%
- Acceleration time will be faster if it is closer to 0 in parameter
- Deceleration time cannot be set

■ No.5 Rotation Direction

- Change motor's rotation direction
- ex) Parameter value is 0: Rotate from FWD signal input to CW
Parameter value is 1: Rotate from FWD signal input to CCW

■ No. 6 Gear Ratio

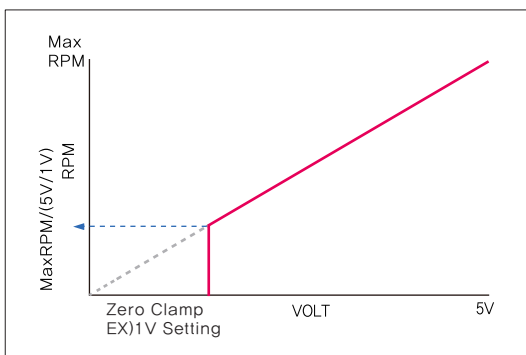
- Input motor gear ratio
- Display RPM from gear output shaft (final output shaft)

■ No. 7 Control Mode

- Select motor speed or torque control
- 0: Operate with speed control mode
- 1: Operate with torque control mode

No.8 Zero Clamp

- Zero Clamp is set from speed command voltage.
- If speed command voltage is in range of zero clamp's set value, motor doesn't operate and if over range of zero clamp's set value, motor operates.

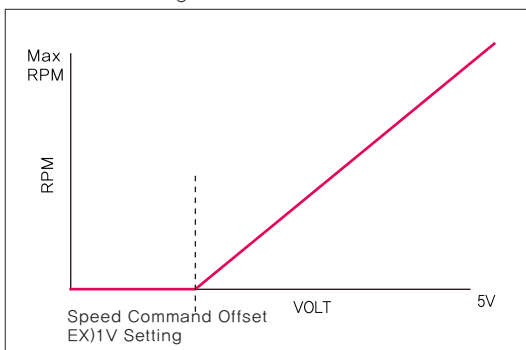


ex) When zero clamp is set to 1V, it recognized to 0 RPM before 1V input. When the voltage is applied to more than 1V,

$$RPM = MaxRPM \times \frac{x}{5V} \quad *x = \text{Speed Command Voltage}$$

■ No.9 Speed command offset

- It is operated more than offset value set from speed command voltage



$$RPM = MaxRPM \times \frac{x - 1V}{5V - 1V}$$

*x = Speed Command Voltage

* x-1V=0 is minimum value

■ No.10 abnormal Signal contact level

- Set output contacts of alarm signal when the alarm occurs in the controller

Setting value 0 : Alarm signal B contact output (normality: Com and short, Alarm: Com and Open)

Setting value 1 : Alarm signal A contact output (normality: Com and Open, Alarm: Com and Short)

■ No.13 Speed control P gain

- Parameter which determines responsibility of speed control
- Vibration and hunting occurs if value is too great

■ No.14 Speed control I gain

- Parameter which determines responsibility of speed control
- Vibration and hunting occurs if value is too great

■ No.20 Communication ID setting

- Select the controller's dialing code at communication control
- Choose the dialing code among 1 ~ 254
- Be careful not to overlap ID if using multiple communications

■ No.21 IO Input Setting

- 0 : IO CN3 switch input control
- 1 : IO input control of RS485 communication

■ No.22 Speed Input Setting

- 0 : IO CN4 variable resistance input control
- 1 : Speed input control of RS485 communication

■ No. 30~32 Internal Speed 1~3

- Operate at speed mode (parameter No.7 : 0)
- Input internal speed setting value in r/min
- If the internal/ external input switch is set to internal input, operation is applied as follows:

Switch 1	Switch 2	Operation
OFF	OFF	External variable resistance speed
ON	OFF	Parameter No.30(Internal speed 1)
OFF	ON	Parameter No.31(Internal speed 2)
ON	ON	Parameter No.32(Internal speed 3)

■ No. 33~35 Internal Torque 1~3

- Operate at torque mode (parameter No.7 : 1)
- Input internal torque setting value in %
- If the internal/ external input switch is set to internal input, operation is applied as follows:

Switch 1	Switch 2	Operation
OFF	OFF	External variable resistance torque
ON	OFF	Parameter No.33(Internal torque 1)
OFF	ON	Parameter No.34(Internal torque 2)
ON	ON	Parameter No.35(Internal torque 3)

DX3000

RS 485 Communication

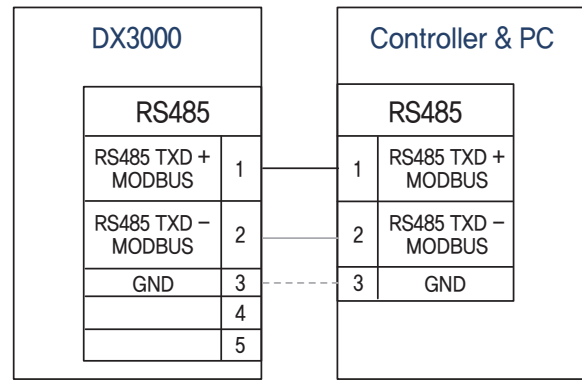
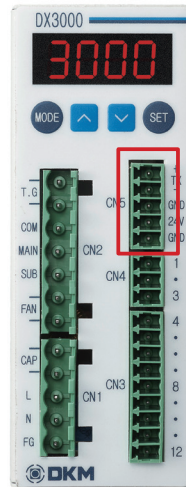
Communication Mode

→ MODBUS RTU Slave Mode

Register Support

- 0x03 (Read Holding Registers)
- 0x04 (Read Input Registers)
- 0x06 (Write Single Registers)
- 0x03 (Read Holding Registers)

Communication Connection Diagram

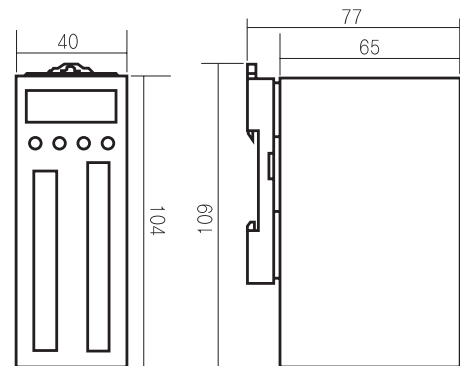


– Please download controller communication manual at our website, www.dkmmotor.com

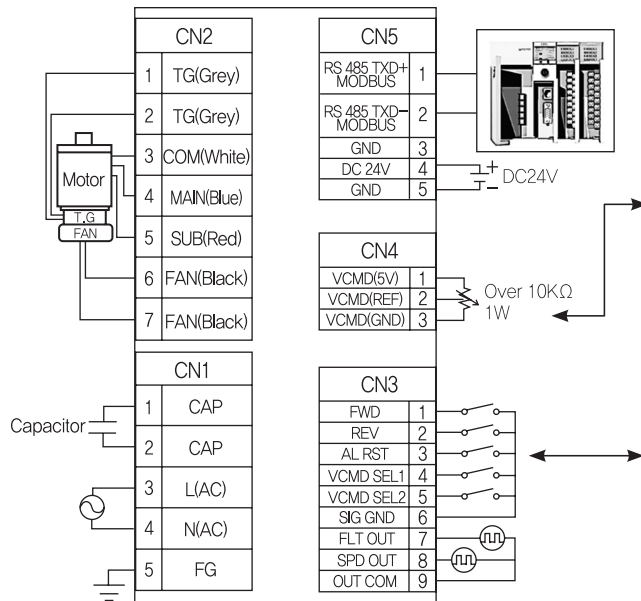
General Specifications

Model		DX3000	
General Specifications	Power supply	Motor Power	AC 220~240V 50Hz / 60Hz ±10%
		Control Power	DC 24V ±10%
	Rated Current [A]	4	
	Max. Current [A]	6	
	Control Function	Speed Control, Torque Control	
	Control mode	Phase-Duty Control	
	Dimension [mm]	40(W) × 104(H) × 65(D)	
	Speed Control Range	50Hz : 100 ~ 1460 r/min 60Hz : 100 ~ 1760 r/min	
	Torque Control Range	0 ~ 100% (Maximum Torque)	
	Feedback Sensor	Tacho - 12 ppr	
Ambient Temperature	-10 °C ~ 55 °C		
Input & Output specifications	Sequence Input	Forward, Reverse, Alarm reset, Velocity select	
	Sequence Output	Speed pulse out, Alarm out	
Built-in functions	Protection Function	Parameter error, AC low voltage alarm, EEPROM	
	Condition Mark	4 Digit Display (7-Segment)	
Communication Mode		Serial Communication (RS485 - MODBUS RTU)	

Dimension



Controller Connection Diagram



Function of CN4 Connector

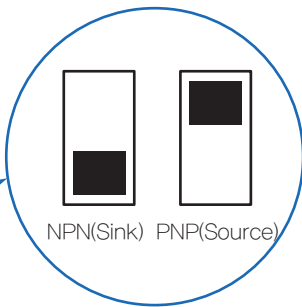
NO.	Name	Description	Remark
1	VCMD V	External speed command potentiometer + voltage output	5V Output
2	VCMD Vref	External speed directive value input	Voltage input
3	VCMD GND	Connect to external speed directive GND	V GND

Function of CN3 Connector

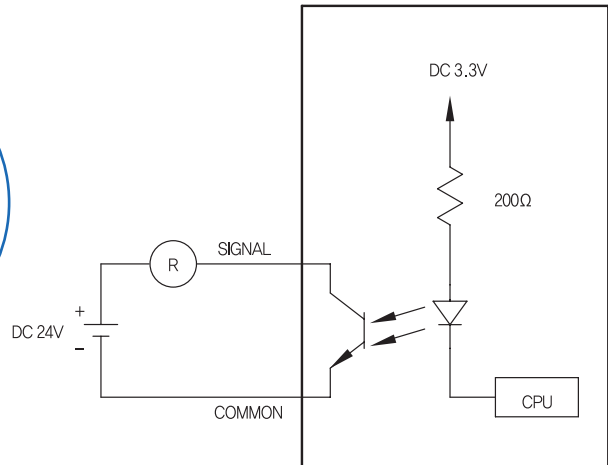
NO.	Name	Description	Remark
1	FORWARD RUN	Input forward switch	Input Signal
2	REVERSE RUN	Input reverse switch	Input Signal
3	ALARM RESET	Input alarm reset switch	Input Signal
4	SPEED SELECT1	Input internal/ external input select switch * Select operation mode with parameter No. 7 * Internal Speed: Parameter No. 30~No. 32 * External Speed: Input external variable resistance	Input Signal
5	SPEED SELECT2	* Internal Torque: Parameter No. 33~No. 35 * External Torque: Input external variable resistance	Input Signal
6	SIGNAL COMMON	Motor switch input COMMON	COMMON
7	FAULT OUT	Output controller status * Change output contact (A or B) according to parameter No. 10	Input Signal
8	SPEED OUT	Motor operating speed output	Input Signal
9	OUT COMMON	Output Contact Common	COMMON

DX3000

I/O Signal Circuit

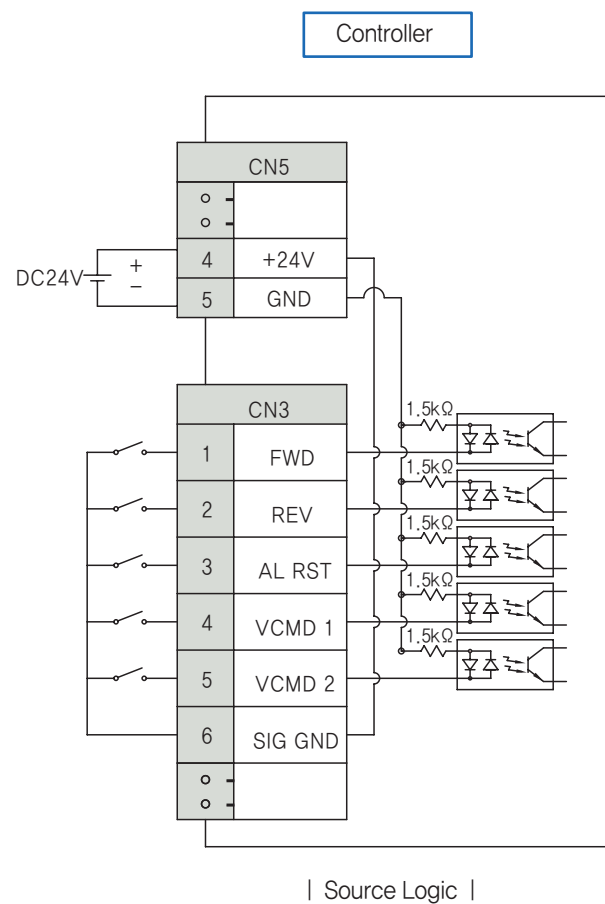
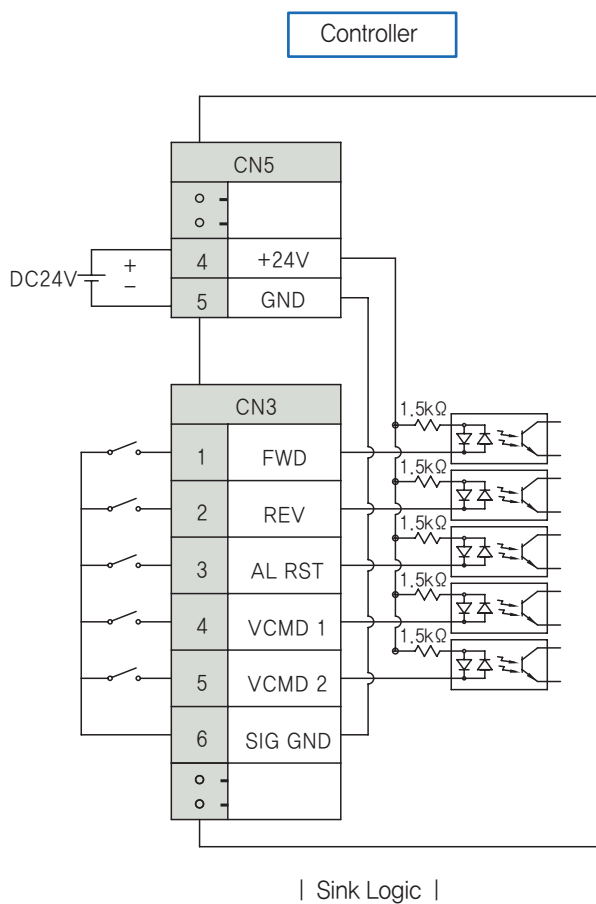


Output Circuit

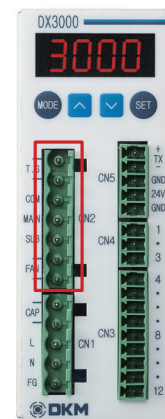
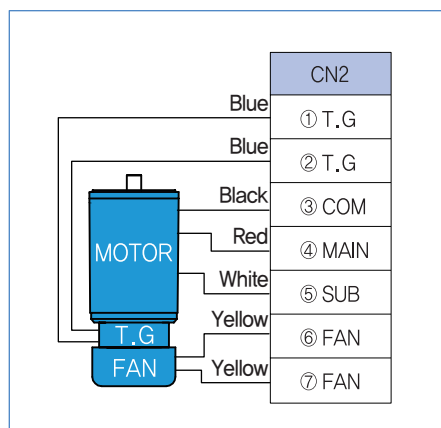
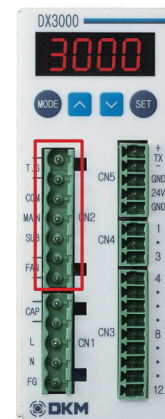
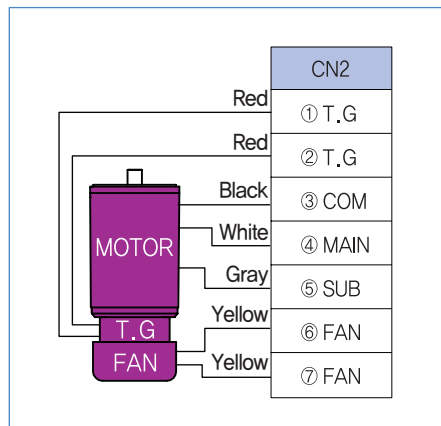
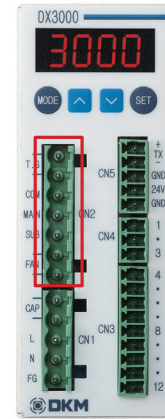
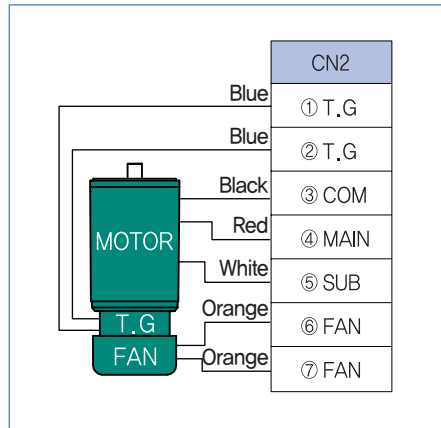


- Input COMMON(NPN, PNP) is set with the bottom switch of controller internal circuit board
- Initial Setting: NPN

Input Circuit



How To Connect Other Brand Motor



- According to the motor type, TG wire(gray*2) and powerful fan wire(black*2) may not be in.
- Please contact us before using other brand motor.

DSA Controller



■ Easy Connection

Operation is possible just by connecting the control unit into power supply after connecting the motor and control unit together using the connector.

■ Easy Operation

The speed can be set easily with the potentiometer on the front panel of the control unit.

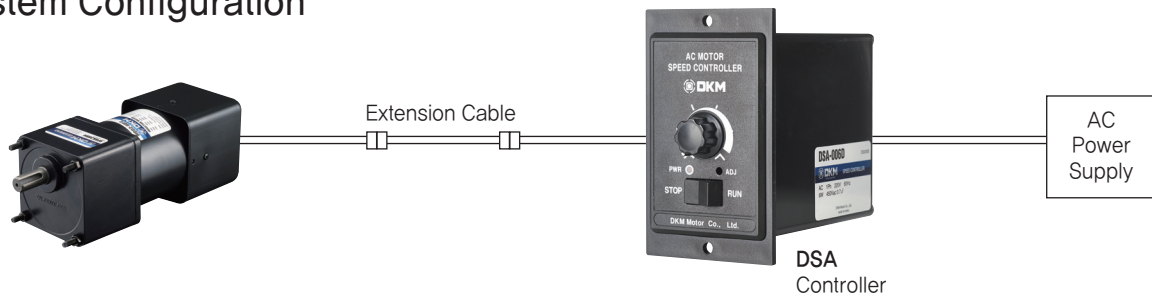
■ Capacitor Built-in

A capacitor for the speed control circuit motor and the speed setting device are assembled in the control unit.

■ Possible to connect with other brand motor

* Other brand motor can be connected to the controller.
Please contact us before use.

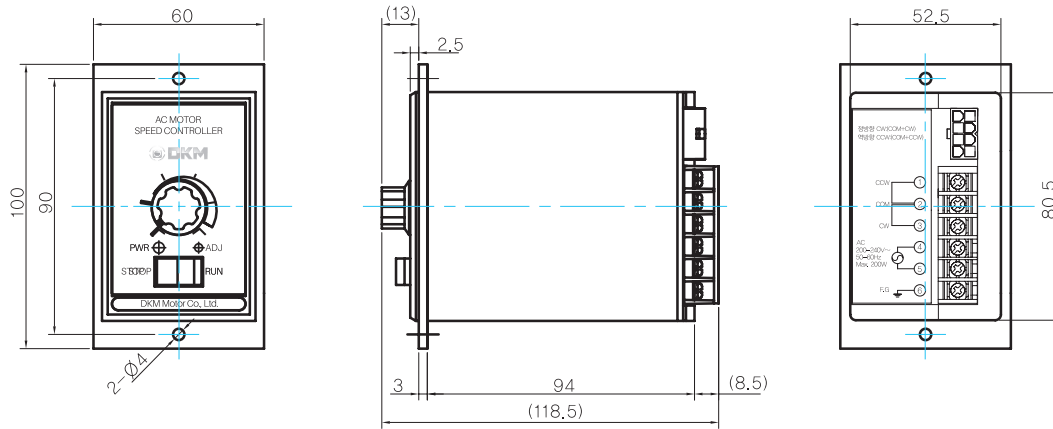
⊗ System Configuration



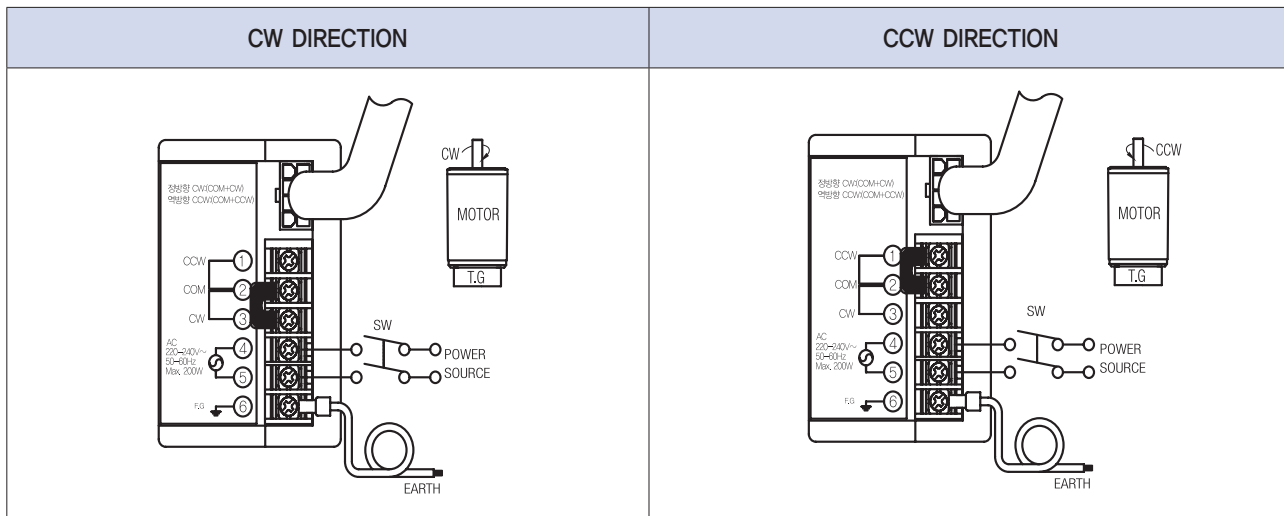
⊗ DSA Specifications

Model	DSA
Rated voltage	AC 220~240V 50/60Hz
Ambient voltage range	±10%
Allowable current	Below 5A
Control	Phase control
Range of speed control	50Hz: 90 ~ 1400 r/min 60Hz: 90 ~ 1700 r/min
Speed control	Operate with volume
Changing rate of speed	±5%(Standard)
Output	6W~180W
Ambient temperature	-10°C ~ 40°C
Ambient humidity	35 ~ 85%RH
Insulation resistance	Over 100MΩ(Base on 500VDC mega)
Dielectric strength	1500VAC 50/60 for 1 minute

Dimensions



Connection Diagram



- 1) Connect control unit and lead wire connector of motor.
- 2) Press stop button before connecting AC power to ④, ⑤ terminals.
- 3) When AC power input, LED lights on.
- 4) CW Direction – Connect ② COM, ③ CW
CCW Direction – Connect ② COM, ① CCW
- 5) Motor RPM is getting faster if speed volume turns to CW and Motor RPM is getting slower if speed volume turns to CCW.
- 6) If operate 'RUN/STOP' switch to STOP, motor is stopped.
Make sure this switch is not same as power ON/OFF.
(When motor has to stop for a long time, extra power switch should be installed.)

DSKM Controller



■ Compact Speed Control Pack

It is compact speed control pack with small plug-in (8-pin) type.

■ Easy Operation

The speed can be set easily with the potentiometer on the front panel of the controller.

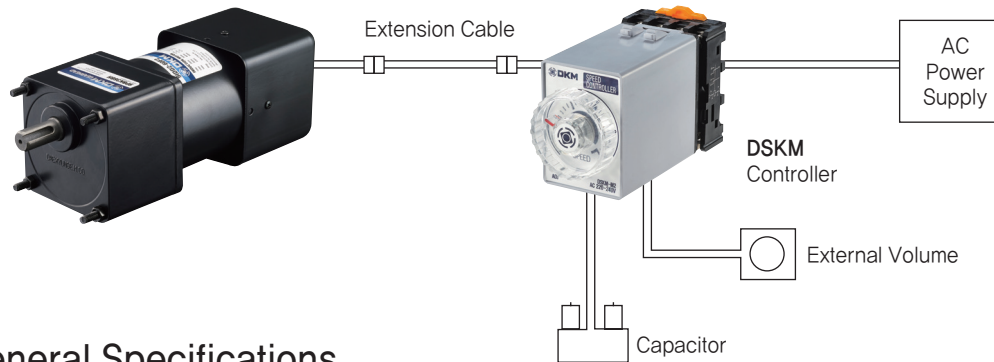
■ External Volume Attachable

The speed can be set easily with the external potentiometer which could be separated from controller body.

■ Various Functions

Bi-directional operation / Variable speed setting / Electric Brake / Multi-stage speed setting

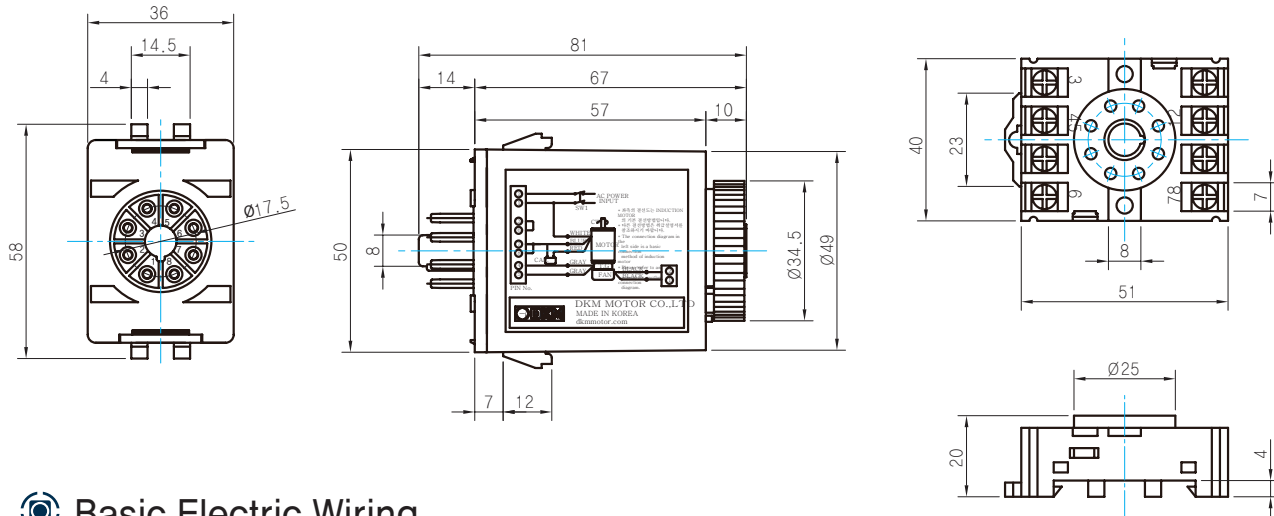
🔗 System Configuration



🔗 General Specifications

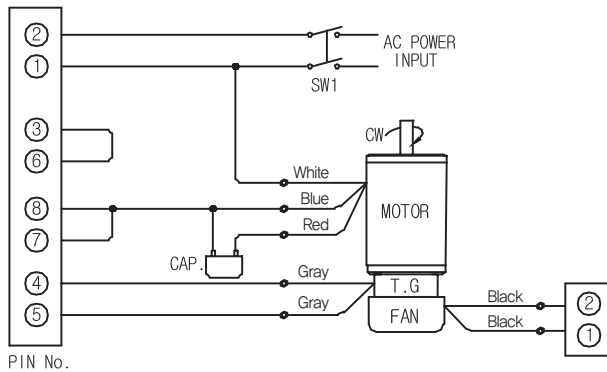
형 명	DSKM-M1	DSKM-M2
Rated voltage	AC 100~120V 50/60Hz	AC 220~240V 50/60Hz
Voltage regulation	±10%	
Power consumption	Below 4 VA	
Control mode	Phase Control	
Operating range	50Hz: 90 ~ 1400 r/min	
	60Hz: 90 ~ 1700 r/min	
Speed setting device	Internal volume (External volume usable)	
Electric brake	Possible to brake for certain period by electric brake	
Electric braking time	0.5second (standard value)	
Ambient temperature	-10°C ~ 55°C	
Ambient humidity	35 ~ 85%RH	
Insulation resistance	Over DC 500V 100MΩ (between power supply and external terminal)	
Dielectric strength	AC 1500V for 1 minute (between the windings and the frame)	

Dimensions



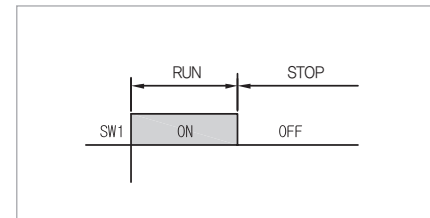
Basic Electric Wiring

| Uni-directional operation + Variable speed |



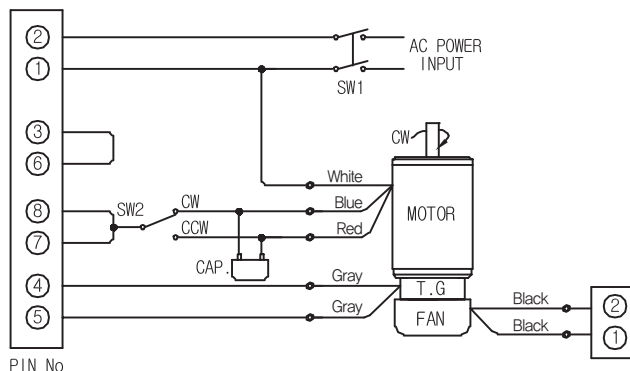
PIN No.

- Exchange wire blue and red of the motor for CCW direction.

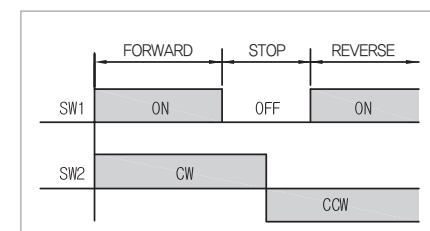


SW1 AC 125V or 250V 5A

| Bi-directional operation + Variable speed |



PIN No



**SW1
SW3** AC 125V or 250V MIN. 5A

- Set stop period and switch SW2 after the motor completely stop.

– DSKM controller has a variety of wiring methods.

Please visit our website or refer to the DSKM manual for electric brake function, external speed setting and multi-step speed setting.